

# Variable Binding, Symmetric Monoidal Closed Theories, and Bigraphs

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

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Concur '09

# Motivation

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SMC categories

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bigraphs

- ▶ In the paper: elementary, algebraic approach to variable binding in the presence of linearity.
- ▶ Here: additional, longer-term motivation, hoping for your feedback.

### Motivation

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SMC categories

Application to  
bigraphs

# Long term goal

Obtain

- ▶ algebraic,
- ▶ geometric, and
- ▶ modular

models of programming languages, with

- ▶ a clear separation between program and execution, e.g.,  
2-dimensional.

What do algebraic, geometric, and modular mean?

# Algebra

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SMC categories

Application to  
bigraphs

Universal algebra  $<$  Lawvere theories  $<$  locally presentable  
categories / sketches.

## Paradox

How algebraic is process algebra?

I here mean definition of their dynamics, not behavioural  
theories.

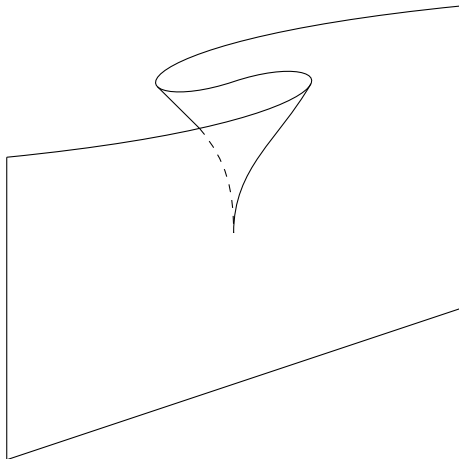
# Geometric

Geometric models of the chosen algebraic structure?  
See John Baez' talk at LICS '09.

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SMC categories

Application to  
bigraphs



# Modular models

Montanari and colleagues (1996) and Mellies (2002) call for **modular** models of programming languages.

- ▶ Understanding programming languages as free **double categories**.
- ▶ **Tiles**, or **cells**, composing vertically and horizontally:

$$\begin{array}{ccc} a & \xrightarrow{f} & b \\ u \downarrow & & \Downarrow \alpha \\ c & \xrightarrow{g} & d \\ & & v \downarrow \end{array}$$

- ▶  $f$  and  $g$  are programs.
- ▶  $\alpha$  is an execution or a reduction.
- ▶  $u$  and  $v$  are side effects, or interactions with the environment.

# Modularity

Such a double category is **modular** when any execution of a composed program

$$\begin{array}{ccccc}
 a & \xrightarrow{f_1} & b' & \xrightarrow{f_2} & b \\
 u \downarrow & & \Downarrow \alpha & & \downarrow v \\
 c & \xrightarrow{g} & & & d
 \end{array}$$

decomposes as

$$\begin{array}{ccccc}
 a & \xrightarrow{f_1} & b' & \xrightarrow{f_2} & b \\
 u \downarrow & & \Downarrow \alpha_1 & & \downarrow v \\
 c & \xrightarrow{g_1} & d' & \xrightarrow{g_2} & d
 \end{array}$$

with  $g_2 g_1 = g$ .

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

# Expected benefits

## Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

- ▶ Montanari et al., Sassone-Sobocinski: bisimulation is automatically a congruence.
- ▶ Melliès: term tracing, rewriting.
- ▶ Hopefully compilation.



# Starting point

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SMC categories

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bigraphs

## Question

What should the horizontal category be?  
Or: what should program composition be?

## Standard answer

Category of contexts:

- ▶ objects: typing contexts  $\Gamma = (x : A, y : B)$ ,
- ▶ morphisms  $\Delta \rightarrow \Gamma$ : assignments

$$[x = e, y = f],$$

- ▶ composition by substitution:

$$\begin{array}{ccc} \Theta & \xrightarrow{\sigma} & \Delta \\ & \searrow & \downarrow [x = e, y = f] \\ & & \Gamma \end{array}$$

$[x = e[\sigma], y = f[\sigma]]$

## Other answers?

Do not plan to use that, for hand-waving reasons:

**Duplication belongs to the dynamics**

Does not model actual plugging of program fragments.

Besides:

**Claim, or thesis**

Duplication in composition hinders geometric intuition.

Hopefully: results will provide more.

# Linear substitution as program composition

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SMC categories

Application to  
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## Proposal

**Linear** substitution as program composition.

I.e., the horizontal category is monoidal ( $\neq$  finite products).

# Linear substitution as program composition

Who tried already?

- ▶ Linear programming languages.
  - ▶ No dynamic duplication either.
  - ▶ But a nice modular model by Melliès, a hint that linearity favours geometric intuition.
- ▶ Bigraphs (Jensen, Milner, ...).
  - ▶ No categorical semantics, esp. for the dynamics.
- ▶ **Premonoidal** or **precartesian** categories (Power, Robinson, Schuermann, ...).
  - ▶ No clear separation between program and execution.
  - ▶ Rather models program equivalence.

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

# Linear substitution as program composition: issues

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SMC categories

Application to  
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- ▶ First issue: can we still handle languages with duplication?

Hopefully yes: bound variables may be used several times, e.g.,  $\lambda x.xx$ .

- ▶ Second issue: linearity is not stable under reduction.

$$(\lambda x.xx)y \longrightarrow yy.$$

# Linear substitution as program composition: issues

Problem:  $(\lambda x.xx)y \longrightarrow yy$ .

## Proposal

Give up reductions, use tiles:

$$\begin{array}{ccc} 1 & \xrightarrow{(\lambda x.xx)y} & 1 \\ c \downarrow & \Downarrow \beta & \downarrow \tau \\ 2 & \xrightarrow{y_1 y_2} & 1. \end{array}$$

The map  $c$  says that  $y$  is duplicated as  $y_1$  and  $y_2$ .

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

# Linear substitution as program composition: issues

Problem:  $(\lambda x.xx)y \longrightarrow yy$ .

## Proposal

Give up reductions, use tiles:

$$\begin{array}{ccccc}
 n & \xrightarrow{f} & 1 & \xrightarrow{(\lambda x.xx)y} & 1 \\
 c_n \downarrow & & \Downarrow c_f & & \Downarrow \beta \\
 2n & \xrightarrow{(f, f)} & 2 & \xrightarrow{y_1 y_2} & 1 \\
 & & c \downarrow & & \downarrow \tau
 \end{array}$$

The map  $c$  says that  $y$  is duplicated as  $y_1$  and  $y_2$ .



# Contents

## Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

Sounds reasonable?

Now, this paper:

- ▶ Linear substitution, in the horizontal category only (no dynamics).
- ▶ Algebraic structure: **symmetric monoidal closed** (SMC) categories.
- ▶ Follow-up on Gadducci's  $GS-\Lambda$ -theories, with:
  - ▶ Use of recent, geometric presentation of the free SMC category (Hughes).
  - ▶ Application to bigraphs.

# Signatures

Formulae from intuitionistic multiplicative linear logic  
(IMLL):

$$A, B, \dots \in \mathcal{F}(X) ::= x \mid I \mid A \otimes B \mid A \multimap B \quad x \in X.$$

## Definition

A (SMC) **signature** is given by:

- ▶ a set  $X$  of **sorts**, and
- ▶ a graph  $\Sigma \xrightarrow{s, t} \mathcal{F}(X)$ .

## Example 1: $\lambda$ -calculus, first take

### Motivation

### Signatures and free SMC categories

### Application to bigraphs

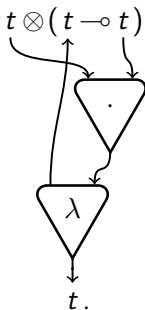
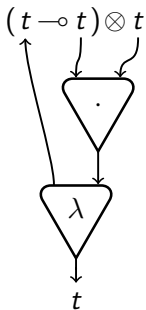
- ▶ One sort  $t$ .
- ▶ Two operations (edges):

$$(t \multimap t) \xrightarrow{\lambda} t \quad \text{and} \quad (t \otimes t) \xrightarrow{\cdot} t.$$

- ▶ Remember HOAS.
- ▶ Here internal to some SMC category.

## The generated SMC category

- ▶ Any  $\Sigma$  freely generates an SMC category  $\mathcal{S}(\Sigma)$ .
  - ▶ Objects: formulae.
  - ▶ Morphisms: IMLL **proof nets**, modulo **Trimble rewiring**.
- ▶ Example, two interpretations for  $\lambda x.(\Box_1 \Box_2)$ :



- ▶ Combinatorial scoping condition generalising the Danos-Regnier criterion for IMLL.

# Back to Example 1

- ▶ Linearity: cannot model  $\lambda x.xx$ .
- ▶ Still:

## Proposition

*Morphisms  $l \longrightarrow t$  are in bijection with closed linear  $\lambda$ -terms.*

## Example 2: $\lambda$ -calculus, second take

Two sorts:

- ▶  $t$  for terms, and
- ▶  $v$  for variables.

Operations:

$$(v \multimap t) \xrightarrow{\lambda} t \qquad (t \otimes t) \xrightarrow{\cdot} t$$

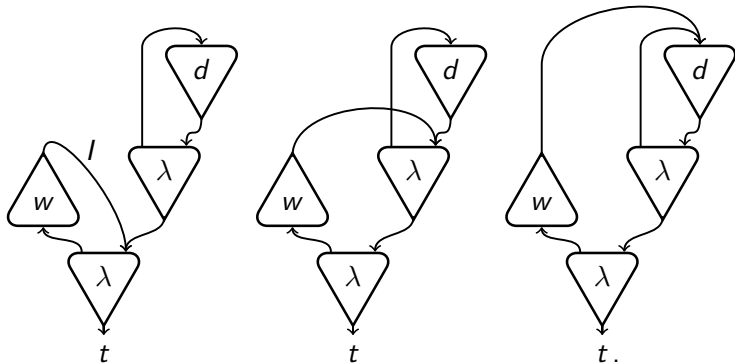
$$v \xrightarrow{d} t \qquad v \xrightarrow{c} v \otimes v \qquad v \xrightarrow{w} I.$$

Reminiscent from weak HOAS and Montanari et al.  
(independently).

This signature uses the unit  $I$ !

# Introducing Trimble rewiring

Identify the proof nets



A weakened variable is linked to anywhere inside its scope, indifferently.

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

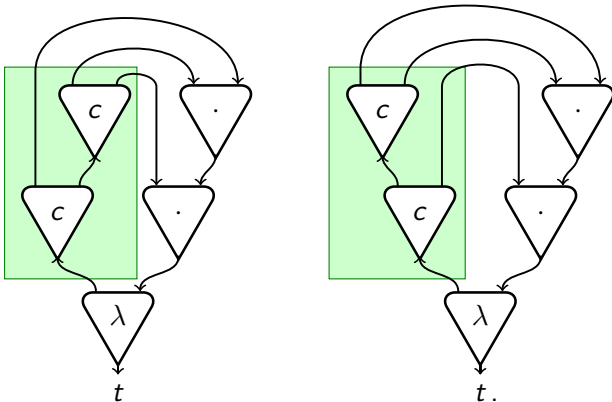
# The need for equations

No bijection with  $\lambda$ -terms, e.g.,  $\lambda x.xxx$ :

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs





# SMC theories

- ▶ Specify equations between morphisms of  $\mathcal{S}(\Sigma)$ .
- ▶ For the  $\lambda$ -calculus: equations making  $(\nu, c, w)$  into a commutative comonoid object yield:

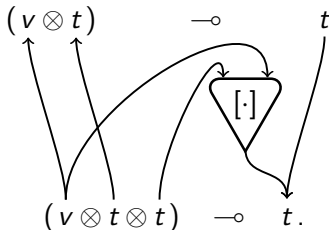
## Theorem

*Morphisms  $l \longrightarrow t$  are in bijection with closed  $\lambda$ -terms.*

Not modulo  $\beta$ ,  $\eta$ , or any equation apart from  $\alpha$ -equivalence.

# Higher-order

- ▶ Theory for *Mobile Ambients*.
- ▶ Ex 1:  $(a, P) \mapsto \text{in } a.P$  becomes  $\text{in}: v \otimes t \rightarrow t$ .
- ▶ Ex 2:  $a[P \mid Q]: v \otimes t \otimes t \rightarrow t$ .
- ▶ Second-order transition: label  $\lambda Q.(a[Q] \mid \square)$ .
- ▶ Expressible as:

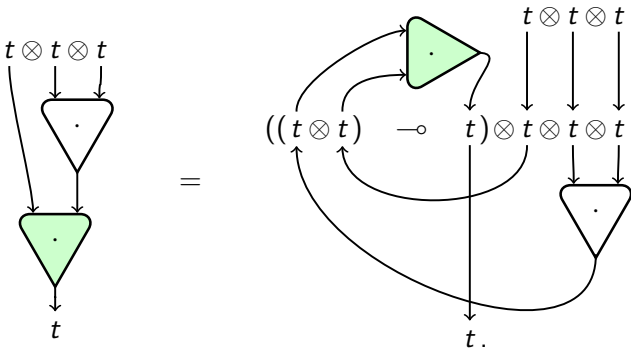


# A curiosity: factorisation

## Proposition

For any (representative of a) proof net  $A \xrightarrow{f} B$  in  $S(\mathcal{T})$  with a set  $C$  of cells, and any partition of  $C$  into  $C_1$  and  $C_2$ ,  $f$  decomposes as  $f_2 \circ f_1$ , where each  $f_i$  contains exactly the cells in  $C_i$ .

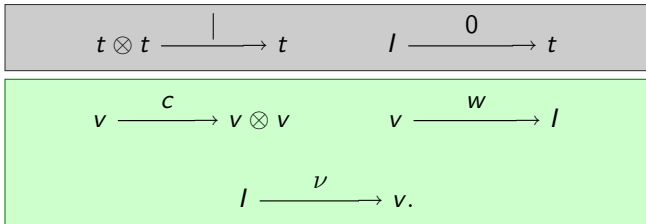
Example:



# Bigraphs in one slide

- ▶ A **bigraphical signature** is an SMC signature  $\Sigma$  containing at least:

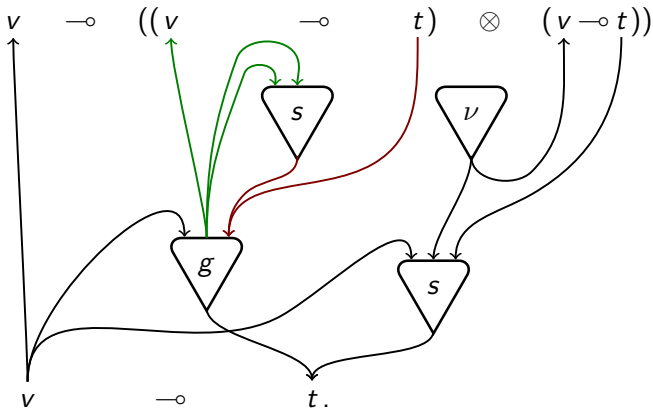
- ▶ two sorts  $t$  and  $v$ ,
- ▶ operations



- ▶ The corresponding category of abstract bigraphs is  $\mathcal{S}(\mathcal{T}_\Sigma)$ , where  $\mathcal{T}_\Sigma$  extends  $\Sigma$  with
  - ▶ equations making  $t$  into a commutative monoid,
  - ▶ equations making  $v$  into a commutative comonoid, and
  - ▶ an equation for  $\nu a.0 \cong 0$ .

# Optimising the representation

E.g., with  $g: v \otimes (v \multimap t) \rightarrow t$  and  $s: v \otimes v \otimes t \rightarrow t$ :



Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

# Corrections

## Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

Of course, that is not exactly true nor fair, we:

- ▶ Forget the **pre**category stuff.
- ▶ Relax from 2nd order signatures.
- ▶ Add objects ( $t \multimap t$ ), but identify others (names vs. indices).
- ▶ Relax the scoping discipline.

# Result 1

But:

- ▶ for any bigraphical signature  $\Sigma$ ,
- ▶ letting  $\mathcal{M}(\Sigma)$  denote Jensen-Milner's category of bigraphs:

## Theorem

*There is a faithful, essentially injective on objects functor  $T: \mathcal{M}(\Sigma) \longrightarrow \mathcal{S}(\mathcal{T}_\Sigma)$ .*

- ▶ Which is neither full, nor surjective on objects (see corrections above).

## Result 2

And the overall scoping discipline is maintained:

### Theorem

$\mathbb{T}$  is full on whole programs, i.e., *ground* bigraphs.

Technically, for any object  $U \in \mathcal{M}(\Sigma)$ , we have

$$\mathcal{S}(\mathcal{T}_\Sigma)(I, \mathbb{T}(U)) \cong \mathcal{M}(\Sigma)(I, U).$$

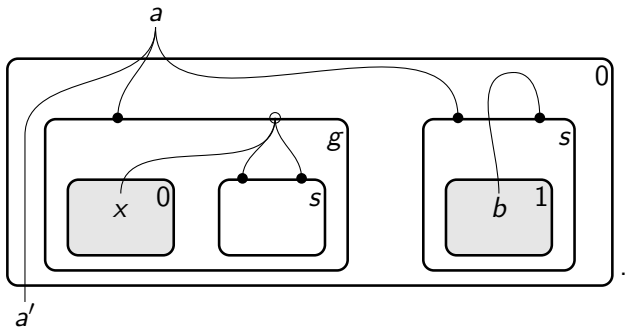


# Illustration

Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

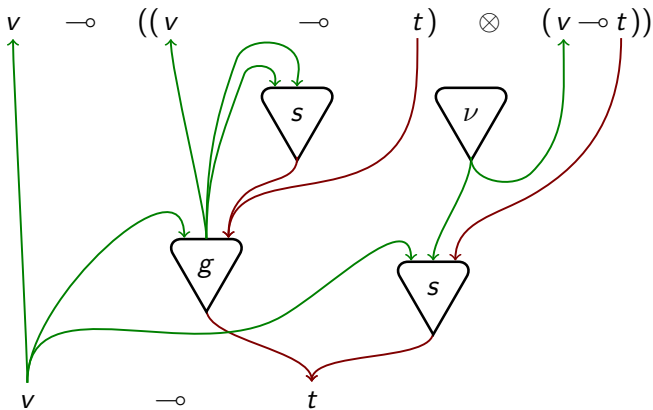


Motivation

Signatures and free  
SMC categories

Application to  
bigraphs

# Illustration



(place graph

vs.

link graph).

## Conclusion

- ▶ SMC theories adequately model syntax with variable binding.
- ▶ Let's move on to the dynamics.

Thanks for your attention.